# An Fixed Point Iterative Method for Tensor Complementarity Problems 

Ping Wei, Jianhua Li, and Xuezhong Wang


#### Abstract

Nonlinear fixed point iterative method for finding a solution of the tensor complementarity problem (TCP) are proposed in this paper. Theoretical analysis shows that tensor complementarity problems are equivalent to a fixed point equation with monotonic increasing odd function. A fixed point iterative method is proposed based on the fixed point equation, and corresponding convergence results are studied. The computer-simulation results further substantiate that the proposed fixed point iterative method can find a solution of the TCP.


Index Terms-Tensor complementarity problem, Fixed point, Iterative method, Convergence.

## I. Introduction

NOWADAYS, nonlinear complementarity problem (NCP) [1] is a popular research topic in the optimization fields [2]. Tensor complementarity problem (TCP) is a subset of the nonlinear complementarity problem (NCP) [1]. Tensor complementarity comes from many application problems, such as the $n$-person game theory [3], [4], [5], [6], hypergraph clustering, etc [1], [7], [8], [9].

For convenience, we use $\mathbb{R}, \mathbb{C}$ and $\mathbb{R}^{[m, n]}$ denote the real field, complex field and all order $m$ and dimensional $n$ real tensor, respectively. Tensors are a high-order extension of matrices, which have the following form

$$
\mathcal{B}=\left(b_{i_{1} i_{2} \ldots i_{m}}\right), b_{i_{1} i_{2} \ldots i_{m}} \in \mathbb{R}, i_{k} \in[n], k \in[m]
$$

We call above multi-array $\mathcal{A}$ as an order $m$ and dimensional $n$ real tensor. Let $\mathbf{z} \in \mathbb{R}^{n}$, then $\mathcal{B} \mathbf{z}^{m-1}$ is a $n$ dimensional vector, which can be defined as [10]:

$$
\begin{equation*}
\left(\mathcal{B} \mathbf{z}^{m-1}\right)_{i}=\sum_{i_{2}, \ldots, i_{m}=1}^{n} b_{i i_{2} \ldots i_{m}} z_{i_{2}} \ldots z_{i_{m}}, i \in[n] \tag{I.1}
\end{equation*}
$$

here $z_{i}$ is the $i$ th entry of the vector $\mathbf{z} . \mathcal{B} \mathbf{z}^{m-2}$ is an $n \times n$ matrix, which can be defined by

$$
\left(\mathcal{B} \mathbf{z}^{m-2}\right)_{i j}=\sum_{i_{3}, \ldots, i_{m}}^{n} b_{i j i_{3}, \ldots, i_{m}} z_{i_{3}} \ldots z_{i_{m}}, i, j \in[n]
$$

For any $\mathcal{B} \in \mathbb{R}^{[m, n]}$ and $\mathbf{y} \in \mathbb{R}^{n}$, the tensor complementarity problem, simplified by $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$, can be stated as: finding $\mathrm{z} \in \mathbb{R}^{n}$ and $\mathbf{z}$ holds

$$
\begin{equation*}
\mathbf{z} \geq \mathbf{0}, \mathcal{B} \mathbf{z}^{m-1}+\mathbf{y} \geq \mathbf{0}, \mathbf{z}^{\top}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)=0 \tag{I.2}
\end{equation*}
$$

[^0]If $\mathcal{B} \in \mathbb{R}^{[2, n]}$ and $\mathbf{y} \in \mathbb{R}^{n}$, then $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ reduces to the linear case and called as linear complementarity problem $\operatorname{LCP}(\mathbf{B}, \mathbf{y})$, that is

$$
\mathbf{z} \geq \mathbf{0}, \mathbf{B} \mathbf{z}+\mathbf{y} \geq \mathbf{0}, \mathbf{z}^{\top}(\mathbf{B} \mathbf{z}+\mathbf{y})=0
$$

Therefore, $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ is a extension of linear case. So far a large number of researchers have focused on this topic [4], [6], [11], [12], [13], [14], [15], [16], [17], [18], [19], [20], [21], [22].
Theoretical results of the $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ have been reported in [4], [6], [11], [12], [13], [14], [15], [16], [17], [19], [20], [21], [22], [23], [24] and the references therein.

Recently, many numerical algorithms for finding the solution of the TCPs have also been provided, such as nonsmooth Newton's method [25], smoothing type algorithms [4], Kojima-Megiddo-Mizuno type continuation method [26], gradient dynamic approach [27], inexact LevenbergMarquardt method [16], mixed integer programming model [28]. Dai [29] proposed a fixed iterative method for solving $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$. The fixed point method has shown many advantages in dealing with nonlinear problems [30], [31], [32]. In this paper, we prove that $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ (I.2) is equivalent to a fixed point equation, which is a extension of the fixed point equation in [29].

This paper arrange the rest parts as follows. In Section II, we review some preliminary background and give some definitions and results. We show that the $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ is equivalent to a fixed point equation in Section III. Some numerical results are considered in Section IV.

## II. Preliminaries

We denote the set $\{1,2,, \ldots, n\}$ by $[n]$ and denote tensor with capital calligraphic letters, for example $\mathcal{B} \in \mathbb{R}^{[m, n]}$. We denote the entries of a tensor $\mathcal{B} \in \mathbb{R}^{[m, n]}$ by $b_{i_{1} i_{2} \ldots i_{m}}$, where $i_{j} \in[n]$ and $j \in[m]$. We denote matrices and vectors by bold capital and bold lower case letters, respectively. Let $\mathbf{A}, \mathbf{B}, \mathbf{T} \in \mathbb{R}^{[2, n]}$ with $\mathbf{A}=\left(a_{i j}\right), \mathbf{B}=\left(b_{i j}\right)$ and $\mathbf{T}=\left(t_{i j}\right)$, $\mathbf{T}=\max \{\mathbf{A}, \mathbf{B}\}$ means $t_{i j}=\max \left\{a_{i j}, b_{i j}\right\}$.

Firstly, we review a useful Lemma as follows.
Lemma II.1. [29] Suppose $\mathbf{z} \in \mathbb{R}^{n}$, we define vector $\mathbf{z}_{+}$as $\left(\mathbf{z}_{+}\right)_{k}=\max \left\{0, z_{k}\right\}, n \in[n]$. Thus for all $\mathbf{w}, \mathbf{v} \in \mathbb{R}^{n}$, the following inequalities hold:

1) $(\mathbf{w}+\mathbf{v})_{+} \leq \mathbf{w}_{+}+\mathbf{v}_{+}$;
2) $\mathbf{w}_{+}-\mathbf{v}_{+} \leq(\mathbf{w}-\mathbf{v})_{+}$;
3) $|\mathbf{w}|=\mathbf{w}_{+}+(-\mathbf{w})_{+}$;
4) $\mathbf{w} \leq \mathbf{v}$ implies $\mathbf{w}_{+} \leq \mathbf{v}_{+}$.

We recall the definitions of eigenvalues and eigenvectors of tensors, which has been introduced by Lim [33] and Qi [10], independently.

Definition II.1. ([10], [33]) Set $\mathcal{B} \in \mathbb{R}^{[m, n]}$. If there exists a vector $\mathbf{z} \in \mathbf{C}^{n} \backslash\{\mathbf{0}\}$ and $\mathbf{z}$ holds

$$
\mathcal{B} \mathbf{z}^{m-1}=\lambda \mathbf{z}^{[m-1]},
$$

we call $\lambda \in \mathbb{C}$ as an eigenvalue of $\mathcal{B}$, where the entries of the vector $\mathbf{z}^{[m-1]}$ are given by

$$
z_{k}^{[m-1]}=z_{k}^{m-1} \text { for } k \in[n]
$$

This nonzero vector $\mathbf{z}$ is the eigenvector associated to eigenvalue $\lambda$.

We recall the following lemma.
Lemma II.2. ([34]) Suppose $\mathbf{u} \in \mathbb{C}^{n} \backslash\{0\}$ and $\mathbf{y} \in \mathbb{C}^{n} \backslash\{0\}$. Then $\frac{1}{\mathbf{z}^{H} \mathbf{z}} \mathbf{y} \mathbf{z}^{H}$ is a solution of the linear system $\mathbf{A z}=\mathbf{y}$.

## III. Fixed point iterative method for TCP

We will prove firstly that $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ is equivalent to a fixed point equation, furthermore, we provide the fixed point iterative method to solve $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ in this section.

## A. Odd and monotonically increasing functions

Let $\mathbf{W}=\left(w_{k s}\right)$, the function $\mathcal{G}(\mathbf{W})$ is defined as $\left(g\left(w_{k s}\right)\right), k, s \in[n]$, where $g(\cdot)$ is an odd and monotonically increasing function (OMIF). We usually take $g(\cdot)$ as the following functions .

Linear function (LF)

$$
g_{\mathrm{lf}}(z)=z ;
$$

Bipolar-sigmoid function ( BsF )

$$
g_{\mathrm{bsf}}(z, r)=\frac{1+\exp (-r)}{1-\exp (-r)} \frac{1-\exp (-r z)}{1+\exp (-r z)}, r>2
$$

Smooth power-sigmoid function (SpsF)

$$
\begin{gathered}
g_{\mathrm{spsf}}(z, r, s)=\frac{1}{2} z^{r}+\frac{1+\exp (-r)}{1-\exp (-r)} \frac{1-\exp (-s z)}{1+\exp (-s z)} \\
r \geq 3, s>2
\end{gathered}
$$

In all, any OMIF $g(\cdot)$ can be used for building of the fixed pint iterative method [35].

## B. Fixed point equation for $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$

We transform the $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ into a fixed point iterative method in this subsection. Dai [29] proposed a fixed equation of the $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ and have the following lemma.
Lemma III.1. [29] Suppose $\mathcal{B} \in \mathbb{R}^{[m, n]}, \mathbf{y} \in \mathbb{R}^{n}$, parameter $\alpha>0$ and $\boldsymbol{\Omega}=\operatorname{diag}\left(d_{1}, d_{2}, \ldots, d_{n}\right)$ with $d_{k}>0, k=$ $1,2, \ldots, n$. Then $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ (I.2) is equivalent to the following equation

$$
\begin{equation*}
\mathbf{z}^{[m-1]}=\left(\mathbf{z}^{[m-1]}-\alpha \boldsymbol{\Omega}\left(\mathcal{B}^{m-1}+\mathbf{y}\right)\right)_{+} \tag{III.1}
\end{equation*}
$$

where $(\mathbf{y})_{+}=\max (\mathbf{y}, \mathbf{0})$.
Notice that, positive diagonal matrix $\Omega$ is a projection operator in equation (III.1). The convergence properties of fixed iterative method (III.1) is determined by $\boldsymbol{\Omega}$. Hence, we extend $\Omega$ in (III.1) to more common forms.

We extend the matrix $\boldsymbol{\Omega}$ to an OMIF $g(\cdot)$ and obtain $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ and fixed point equation are equivalent.

Theorem III.1. Suppose $\mathcal{B} \in \mathbb{R}^{[m, n]}, \mathbf{y} \in \mathbb{R}^{n}, \alpha>0$ and $g(\cdot)$ be a OMIF. Then $\operatorname{TCP}(\mathcal{B}, \mathbf{y})(I .2)$ is equivalent to the following equation

$$
\begin{equation*}
\mathbf{z}^{[m-1]}=\left(\mathbf{z}^{[m-1]}-\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{+} \tag{III.2}
\end{equation*}
$$

Proof: Because $g(\cdot)$ is an odd function, we have $g\left(-z_{i}\right)=-g\left(z_{i}\right)$ and

$$
g\left(z_{i}\right)\left\{\begin{array}{l}
\geq 0, \text { for } z_{i} \geq 0 \\
<0, \text { for } z_{i}<0
\end{array}\right.
$$

Suppose that $\mathbf{z}$ is a solution of $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$. If $z_{i}=0$ and $\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)_{i} \geq 0$, integrate with $g(\cdot)$ is a monotonically increasing function, we immediately obtain

$$
\begin{aligned}
& z_{i}^{m-1}-\left(z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}\right)_{+} \\
& =-\left(-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}\right)_{+}=0
\end{aligned}
$$

If $\left(\mathcal{B} \mathbf{z}^{m-1}-\mathbf{y}\right)_{i}=0$ and $z_{i} \geq 0$, then

$$
\begin{aligned}
& z_{i}^{m-1}-\left(z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}\right)_{+} \\
& =z_{i}^{m-1}-z_{i}^{m-1}=0
\end{aligned}
$$

Conversely, assume that (III.2) holds. Notice that

$$
\mathbf{z}^{[m-1]}=\left(\mathbf{z}^{[m-1]}-\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{+} \geq \mathbf{0}
$$

we have $\mathcal{B} \mathbf{z}^{m-1}-\mathbf{y} \geq \mathbf{0}$. In fact, if $\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)_{i}<\mathbf{0}$ for some $i$, then

$$
\begin{aligned}
0 & =z_{i}^{m-1}-\left(z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}\right)_{+} \\
& =\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}<0
\end{aligned}
$$

which is a contradiction. For one hand, if

$$
z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i} \geq 0
$$

then,

$$
\begin{aligned}
0 & =z_{i}^{m-1}-\left(z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}\right)_{+} \\
& =\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}
\end{aligned}
$$

Based on $g(\cdot)$ is an odd function, we have $\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)_{i}=0$. Therefore

$$
z_{i}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)_{i}=0
$$

For the other hand, if

$$
z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}<0
$$

then,

$$
0=z_{i}^{m-1}-\left(z_{i}^{m-1}-\alpha\left(\mathcal{G}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)\right)_{i}\right)_{+}=z_{i}^{m-1}
$$

which shows

$$
z_{i}\left(\mathcal{B} \mathbf{z}^{m-1}+\mathbf{y}\right)_{i}=0
$$

This completes the proof.

## C. Fixed point iterative method for $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$

In this subsection, we attain a general fixed point iterative method to solve $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ based on fixed point equation (III.2) as follows.

$$
\begin{equation*}
\mathbf{z}_{k+1}=\left[\left(\mathbf{z}_{k}^{[m-1]}-\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}_{k}^{m-1}+\mathbf{y}\right)\right)_{+}\right]^{\left[\frac{1}{m-1}\right]} \tag{III.3}
\end{equation*}
$$

Next, we consider the convergence properties on the proposed iterative method. We first have the following lemma for the fixed point iterative method (III.3).
Lemma III.2. Let $\mathcal{B} \in \mathbb{R}^{[m, n]}$. For any $\mathbf{y} \in \mathbb{R}^{n}$, the iterative sequence $\left\{\mathbf{z}_{k}\right\}$ satisfy the recursive inequality

$$
\begin{equation*}
\left|\mathbf{z}_{k+1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]}\right| \leq\left|\mathbf{I}-\alpha \mathbf{y}_{k}\right|\left|\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right| \tag{III.4}
\end{equation*}
$$

where $\mathbf{y}_{k}$ satisfies
$\mathcal{G}\left(\mathcal{B} \mathbf{z}_{k}^{m-1}+\mathbf{y}\right)-\mathcal{G}\left(\mathcal{B} \mathbf{z}_{k-1}^{m-1}+\mathbf{y}\right)=\mathbf{y}_{k}\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right)$.
Proof: Based on fixed point iterative formula (III.3), we obtain the following relation

$$
\begin{aligned}
\mathbf{z}_{k+1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]} & =\left(\mathbf{z}_{k}^{[m-1]}-\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}_{k}^{m-1}+\mathbf{y}\right)\right)_{+} \\
& -\left(\mathbf{z}_{k-1}^{[m-1]}-\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}_{k-1}^{m-1}+\mathbf{y}\right)\right)_{+} \\
& \leq\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}-\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}_{k}^{m-1}\right.\right. \\
& \left.+\mathbf{y})+\alpha \mathcal{G}\left(\mathcal{B} \mathbf{z}_{k-1}^{m-1}+\mathbf{y}\right)\right)_{+} \\
& \leq \mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1]}^{m-1]}-\alpha\left[\mathcal { G } \left(\mathcal{B} \mathbf{z}_{k}^{m-1}\right.\right. \\
& \left.+\mathbf{y})-\mathcal{G}\left(\mathcal{B} \mathbf{z}_{k-1}^{m-1}+\mathbf{y}\right)\right]_{+} .
\end{aligned}
$$

By Lemma II.2, we have

$$
\begin{aligned}
\mathbf{z}_{k+1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]} \leq & \left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right. \\
& \left.-\alpha \mathbf{y}_{k}\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right)\right)_{+} \\
= & \left(\left(\mathbf{I}-\mathbf{y}_{k}\right)\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right)\right)_{+}
\end{aligned}
$$

and then

$$
\begin{equation*}
\left(\mathbf{z}_{k+1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]}\right)_{+} \leq\left(\left(\mathbf{I}-\mathbf{y}_{k}\right)\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right)\right)_{+} \tag{III.5}
\end{equation*}
$$

Analogously, we have

$$
\begin{equation*}
\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k+1}^{[m-1]}\right)_{+} \leq\left(\left(\mathbf{I}-\mathbf{y}_{k}\right)\left(\mathbf{z}_{k-1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]}\right)\right)_{+} \tag{III.6}
\end{equation*}
$$

Since $|\mathbf{z}|=(\mathbf{z})_{+}+(-\mathbf{z})_{+}$, combining (III.5) and (III.6), we obtain

$$
\begin{align*}
\left|\mathbf{z}_{k+1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]}\right| & \leq\left|\left(\mathbf{I}-\mathbf{y}_{k}\right)\left(\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right)\right| \\
& \leq\left|\mathbf{I}-\mathbf{y}_{k}\right|\left|\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right| \tag{III.7}
\end{align*}
$$

We complete the proof.
Based on Lemma III.2, we can attain the convergence result on the proposed fixed point iterative method.

Theorem III.2. Assume that $\mathcal{B} \in \mathbb{R}^{[m, n]}$. If $\rho(\mathbf{T})<1$, then the iterative sequence $\left\{\mathbf{z}_{k}\right\}$ generated by the fixed point iterative method (III.3) converges to a solution of the $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ for any $\mathbf{y} \in \mathbb{R}^{n}$ and initial guess vector $\mathbf{z}_{0} \in \mathbb{R}^{n}$,, where $\mathbf{T}=\max _{1 \leq k}\left\{\mathbf{T}_{k}\right\}$ and $\mathbf{T}_{k}=\left|\mathbf{I}-\mathbf{y}_{k}\right|$.

Proof: Our purpose is to explain

$$
\lim _{k \rightarrow+\infty}\left|\mathbf{z}_{k+1}^{[m-1]}-\mathbf{z}_{k}^{[m-1]}\right|=0
$$

Set $\mathbf{T}=\max _{1 \leq k}\left\{\left|\mathbf{I}-\mathbf{y}_{k}\right|\right\}$. From

$$
\begin{aligned}
\left|\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{0}^{[m-1]}\right| \leq & \leq\left|\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{k-1}^{[m-1]}\right|+\mid \mathbf{z}_{k-1}^{[m-1]} \\
& -\mathbf{z}_{k-2}^{[m-1]}\left|+\ldots+\left|\mathbf{z}_{1}^{[m-1]}-\mathbf{z}_{0}^{[m-1]}\right| .\right.
\end{aligned}
$$

Together with inequality (III.4) in Lemma III. 2 with $\mathbf{T}=$ $\max _{1 \leq k}\left\{\mathbf{T}_{k}\right\}$ and $\mathbf{T}_{k}=\left|\mathbf{I}-\mathbf{y}_{k}\right|$, this lead to

$$
\begin{aligned}
\left|\mathbf{z}_{k}^{[m-1]}-\mathbf{z}_{0}^{[m-1]}\right| & \leq\left(\mathbf{T}_{k-1} \mathbf{T}_{k-2} \ldots \mathbf{T}_{2} \mathbf{T}_{1}+\mathbf{T}_{k-2} \ldots \mathbf{T}_{2}\right. \\
& \left.\mathbf{T}_{1}+\ldots+\mathbf{T}_{1}+\mathbf{I}\right)\left|\mathbf{z}_{1}^{[m-1]}-\mathbf{z}_{0}^{[m-1]}\right| \\
& \leq\left(\mathbf{T}^{k-1}+\ldots+\mathbf{I}\right)\left|\mathbf{z}_{1}^{[m-1]}-\mathbf{z}_{0}^{[m-1]}\right| \\
& \leq(\mathbf{I}-\mathbf{T})^{-1}\left|\mathbf{z}_{1}^{[m-1]}-\mathbf{z}_{0}^{[m-1]}\right|,
\end{aligned}
$$

it follows from $\mathbf{T}$ is a nonnegative matrix and $\rho(\mathbf{T})<1$.
Employing the same approach of the proof of Theorem 3.1 in [29], we can show the iterative sequence $\left\{\mathbf{z}_{k}\right\}$ converges to a solution of $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$. So it is omitted. The proof is completed.

## IV. Test examples

We show the efficacy of the proposed iterative method for solving $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ by using two numerical examples. We compare proposed fixed point iterative method and method I present in [29] on iterative numbers and CPU times in this section,. In all tables, we use 'LF', 'BsF', 'SpsF' and 'M-I' denote the proposed fixed point iterative method with LF, BsF, SpsF and method I present in [29], respectively.

Let

$$
\begin{equation*}
\operatorname{Err}=\left\|\mathbf{z}_{k}-\mathbf{z}_{k-1}\right\|_{2} . \tag{IV.1}
\end{equation*}
$$

In our numerical tests, we take the stopping criteria as Err $<$ $10^{-12}$ or iteration number is less than 1000 times.

In the following two tests, we take vector $\mathbf{y} \in \mathbb{R}^{n}$ with $y_{i}=(-1)^{i} i$ for $i \in[n]$ and initial vector $\mathbf{z}_{0}=(1,1, \ldots, 1)^{\top}$. We compare superiority of the proposed iterative method and method I [29] with $\alpha=1$ for solving $\operatorname{TCP}(\mathcal{B}, \mathbf{y})$ with different order $m$ and dimension $n$, where BsF is $f_{b s f}(v, 3)$ and $\operatorname{SpsF}$ is $f_{\text {spsf }}(v, 5,7)$.
Example IV.1. Let tensor $\mathcal{B} \in \mathbb{R}^{[n, n]}$ with

$$
b_{k_{1} \ldots k_{m}}=\left|\sin \left(k_{1}+k_{2}+\ldots+k_{m}\right)\right|
$$

then $\mathcal{B}=n^{m-1} \mathcal{I}-\mathcal{B}$ is a nonsingular tensor, it follows from [36], [37], where $\mathcal{I}$ is a real unit tensor.
Example IV.2. Let $\mathcal{C} \in \mathbb{R}^{[m, n]}$ be a randomized tensor whose elements obey standard uniform distribution on $(0,1)$. Suppose

$$
\lambda=(1+\epsilon) \max _{i=1,2, \cdots, n}\left(\mathcal{C} \mathbf{u}^{2}\right)_{i}, \epsilon>0
$$

where $\mathbf{u}=(1,1, \cdots, 1)^{\top}$. Then $\mathcal{B}=|\lambda \mathcal{I}-\mathcal{C}|$ is $a$ nonsingular $\mathcal{H}$-tensor [37].

The computer simulations show that the fixed point iterative method with nonlinear function can solve TCP effectively. Moreover, the convergence property of the proposed fixed point iterative method performs better than that of the corresponding the method I in [29].

## REFERENCES

[1] F. Facchinei and J. Pang, Finite-dimensional variational inequalities and complementarity problems. Springer Science \& Business Media, 2007.
[2] M. Parwadi, "Polynomial penalty method for solving linear programming problems," IAENG International Journal of Applied Mathematics, vol. 40, no. 3, pp. 167-171, 2010.
[3] C. Chen and L. Zhang, "Finding nash equilibrium for a class of multiperson noncooperative games via solving tensor complementarity problem," Applied Numerical Mathematics, vol. 145, pp. 458-468, 2019.
[4] Z. Huang and L. Qi, "Formulating an n-person noncooperative game as a tensor complementarity problem," Computational Optimization and Applications, vol. 66, no. 3, pp. 557-576, 2017.
[5] _ ,"Tensor complementarity problems-part III: Applications," Journal of Optimization Theory and Applications, vol. 183, no. 3, pp. 1-21, 2019.
[6] Z. Luo, L. Qi, and N. Xiu, "The sparsest solutions to $\mathcal{Z}$-tensor complementarity problems," Optimization Letters, vol. 11, no. 3, pp. 471-482, 2017.
[7] R. Cottle, J. Pang, and R. Stone, The Linear Complementarity Problem. Academic Press, Boston, 1992.
[8] M. Gowda and J. Pang, "Stability analysis of variational inequalities and nonlinear complementarity problems, via the mixed linear complementarity problem and degree theory," Mathematics of Operations Research, vol. 19, no. 4, pp. 831-879, 1994.
[9] N. Lu, Z. Huang, and J. Han, "Properties of a class of nonlinear transformations over euclidean jordan algebras with applications to complementarity problems," Numerical Functional Analysis and Optimization, vol. 30, no. 7-8, pp. 799-821, 2009.
[10] L. Qi, "Eigenvalues of a real supersymmetric tensor," J. Symbolic Comput., vol. 40, no. 6, pp. 1302-1324, 2005. [Online]. Available: http://dx.doi.org/10.1016/j.jsc.2005.05.007
[11] Y. Song and L. Qi, "Properties of some classes of structured tensors," Journal of Optimization Theory and Applications, vol. 165, no. 3, pp. 854-873, 2015.
[12] X. Bai, Z. Huang, and Y. Wang, "Global uniqueness and solvability for tensor complementarity problems," Journal of Optimization Theory and Applications, vol. 170, no. 1, pp. 72-84, 2016.
[13] M. Che, L. Qi, and Y. Wei, "Positive-definite tensors to nonlinear complementarity problems," Journal of Optimization Theory and Applications, vol. 168, no. 2, pp. 475-487, 2016.
[14] - , "Stochastic $R_{0}$ tensors to stochastic tensor complementarity problems," Optimization Letters, vol. 13, no. 2, pp. 261-279, Mar 2019. [Online]. Available: https://doi.org/10.1007/s11590-018-1362-7
[15] W. Ding, Z. Luo, and L. Qi, "P-tensors, $P_{0}$-tensors, and tensor complementarity problem," Linear Algebra and its Application, vol. 555, pp. 336-354, 2018.
[16] S. Du, L. Zhang, C. Chen, and L. Qi, "Tensor absolute value equations," Science China Mathematics, vol. 61, pp. 1695-1710, 2018.
[17] M. Gowda, Z. Luo, L. Qi, and N. Xiu, "Z-tensors and complementarity problems," arXiv:1510.07933.
[18] Y. Tanaka, "Proof of constructive version of the fan-glicksberg fixed point theorem directly by sperner's lemma and approximate nash equilibrium with continuous strategies: A constructive analysis," IAENG International Journal of Applied Mathematics, vol. 41, no. 2, pp. 133140, 2011.
[19] Y. Song and L. Qi, "Tensor complementarity problem and semipositive tensors," Journal of Optimization Theory and Applications, vol. 169, pp. 1069-1078, 2016.
[20] X. Wang, M. Che, and Y. Wei, "Neural networks based approach solving multi-linear systems with $\mathcal{M}$-tensors," Neurocomputing, vol. 351, pp. 33-42, 2019.
[21] S. Xie, D. Li, and H. Xu, "An iterative method for finding the least solution to the tensor complementarity problem," Journal of Optimization Theory and Applications, vol. 175, no. 1, pp. 119-136, 2017.
[22] H. Xu, D. Li, and S. Xie, "An equivalent tensor equation to the tensor complementarity problem with positive semi-definite $\mathcal{Z}$-tensor," Optimization Letters, vol. 13, pp. 685-694, 2019.
[23] W. Yu, C. Ling, and H. He, "On the properties of tensor complementarity problems," vol. arXiv:1608.01735v3, 2018.
[24] Y. Song and L. Qi, "Properties of tensor complementarity problem and some classes of structured tensors," Annals of Applied Mathematics, no. 3, pp. 308-323, 2017.
[25] D. Liu, W. Li, and S. W. Vong, "Tensor complementarity problems: the GUS-property and an algorithm," Linear and Multilinear Algebra, vol. 28, pp. 1726-1749, 2018.
[26] L. Han, "A continuation method for tensor complementarity problems," Journal of Optimization Theory and Applications, vol. 180, no. 3, pp. 949-963, 2019.
[27] X. Wang, M. Che, L. Qi, and Y. Wei, "Modified gradient dynamic approach to the tensor complementarity problem," Optimization Methods and Software, vol. 35, pp. 394-415, 2020.
[28] S. Du and L. Zhang, "A mixed integer programming approach to the tensor complementarity problem," Journal of Global Optimization, vol. 73, no. 4, pp. 789-800, 2019.
[29] P. Dai, "A fixed point iterative method for tensor complementarity problems," Journal of Scientific Computing, vol. 84, no. 3, pp. 1-20, 2020.
[30] Y. Tanaka, "Various notions about constructive brouwer's fixed point theorem," IAENG International Journal of Applied Mathematics, vol. 42, no. 3, pp. 152-154, 2012.
[31] M. Arshad, A. Azam, and P. Vetro, "Common fixed point of generalized contractive type mappings in cone metric spaces," IAENG International Journal of Applied Mathematics, vol. 41, no. 3, pp. 246251, 2011.
[32] Y. Tanaka, "Constructive proof of the fan-glicksberg fixed point theorem for sequentially locally non-constant multi-functions in a locally convex space," IAENG International Journal of Computer Science, vol. 40, no. 1, pp. 1-6, 2013.
[33] L. Lim, "Singular values and eigenvalues of tensors: A variational approach," in IEEE CAMSAP 2005: First International Workshop on Computational Advances in Multi-Sensor Adaptive Processing. IEEE, 2005, pp. 129-132.
[34] G. Ouyang, "The general solution for inverse problem of system of linear equation $\mathbf{A x}=\mathbf{b}, "$ Mathematical Theory and Application, vol. 24, no. 2, pp. 26-28, 2004.
[35] X. Wang, H. Ma, and P. S. Stanimirović, "Nonlinearly activated recurrent neural network for computing the drazin inverse," Neural Processing Letters, vol. 46, pp. 1-23, 2017.
[36] W. Ding, L. Qi, and Y. Wei, " $\mathcal{M}$-tensors and nonsingular $\mathcal{M}$-tensors," Linear Algebra and Its Applications, vol. 439, no. 10, pp. 3264-3278, 2013.
[37] W. Ding and Y. Wei, "Solving multi-linear systems with $\mathcal{M}$-tensors," Journal of Scientific Computing, vol. 68, no. 2, pp. 689-715, 2016.

TABLE I
The comparison results on present method and method I [29] for Example IV.1.

|  | LF |  |  | BsF |  |  | SpsF |  |  | M-I |  |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $(m, n)$ | $\alpha$ | Ite | CPU | $\alpha$ | Ite | CPU | $\alpha$ | Ite | CPU | Ite | CPU |
| $(3,2)$ | 0.2 | 22 | 0.0239 | 0.162 | 15 | 0.0158 | 0.162 | 9 | 0.0110 | 9 | 0.0155 |
| $(3,4)$ | 0.06 | 19 | 0.0169 | 0.035 | 19 | 0.0155 | 0.035 | 11 | 0.0106 | 21 | 0.0309 |
| $(3,10)$ | 0.012 | 22 | 0.0167 | 0.005 | 17 | 0.0138 | $1 \mathrm{E}-4$ | 10 | 0.0082 | 35 | 0.0458 |
| $(3,15)$ | 0.006 | 28 | 0.0214 | 0.005 | 18 | 0.0139 | $1 \mathrm{E}-5$ | 8 | 0.0074 | 26 | 0.0346 |
| $(3,100)$ | $1 \mathrm{E}-4$ | 33 | 0.0431 | $1 \mathrm{E}-4$ | 20 | 0.0290 | $1 \mathrm{E}-8$ | 8 | 0.0122 | 52 | 0.0654 |
| $(4,4)$ | 0.017 | 18 | 0.0194 | 0.012 | 12 | 0.0113 | $1 \mathrm{E}-3$ | 7 | 0.0061 | 20 | 0.0184 |
| $(4,10)$ | 0.001 | 24 | 0.0203 | 0.01 | 11 | 0.0101 | $1 \mathrm{E}-5$ | 5 | 0.0051 | 24 | 0.1754 |
| $(4,15)$ | $3 \mathrm{E}-4$ | 23 | 0.0183 | 0.01 | 10 | 0.0088 | $1 \mathrm{E}-5$ | 7 | 0.0063 | 25 | 0.1564 |
| $(4,100)$ | $1.2 \mathrm{E}-6$ | 29 | 1.3950 | $1 \mathrm{E}-4$ | 14 | 0.6764 | $1 \mathrm{E}-8$ | 7 | 0.3567 | 34 | 2.8439 |

TABLE II
The comparison results on present method and method I [29] For Example IV.2.

|  | Lin |  |  | Bs |  |  | Sps |  |  | M-I |  |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $(m, n)$ | $\alpha$ | Ite | CPU | $\alpha$ | Ite | CPU | $\alpha$ | Ite | CPU | Ite | CPU |
| $(3,2)$ | 0.5 | 17 | 0.0184 | 0.6 | 10 | 0.0098 | 0.4 | 12 | 0.0121 | 17 | 0.0188 |
| $(3,4)$ | 0.15 | 34 | 0.0324 | 0.1 | 25 | 0.0252 | $1 \mathrm{E}-3$ | 29 | 0.0308 | 32 | 0.0624 |
| $(3,10)$ | 0.02 | 32 | 0.0271 | 0.01 | 17 | 0.0145 | $1 \mathrm{E}-4$ | 14 | 0.0131 | 52 | 0.0742 |
| $(3,15)$ | 0.02 | 33 | 0.0338 | 0.015 | 18 | 0.0219 | $4 \mathrm{E}-5$ | 14 | 0.0222 | 46 | 0.0689 |
| $(3,100)$ | $2.5 \mathrm{E}-4$ | 50 | 0.0595 | $1.5 \mathrm{E}-3$ | 17 | 0.0223 | $4 \mathrm{E}-8$ | 12 | 0.0179 | 78 | 0.1562 |
| $(4,4)$ | 0.002 | 43 | 0.0367 | 0.015 | 11 | 0.0103 | $4 \mathrm{E}-4$ | 9 | 0.0123 | 45 | 0.0598 |
| $(4,10)$ | 0.001 | 24 | 0.0203 | $1.5 \mathrm{E}-3$ | 11 | 0.0112 | $4 \mathrm{E}-5$ | 6 | 0.0068 | 98 | 0.1632 |
| $(4,15)$ | $6.5 \mathrm{E}-4$ | 47 | 0.0391 | $1 \mathrm{E}-3$ | 13 | 0.0113 | $2 \mathrm{E}-5$ | 9 | 0.0087 | 125 | 0.2653 |
| $(4,50)$ | $2 \mathrm{E}-5$ | 74 | 0.2419 | $1.5 \mathrm{E}-4$ | 13 | 0.0480 | $1.5 \mathrm{E}-7$ | 7 | 0.0278 | 203 | 1.2598 |


[^0]:    Manuscript received March 03, 2022; revised October 31, 2022.
    This work was supported by the National Natural Science Foundation of China under grant 12061032; Faculty Research Grants Awarded by Principal's Funds CXTD2022010.
    P. Wei is a professor of School of Mathematics and Statistics, Hexi University, Zhangye, 734000, P. R. of China. Email:weiping2003like@163.com.
    J. Li is a professor of School of Mathematics and Statistics, Hexi University, Zhangye, 734000, P. R. of China. E-mail:lijh129@163.com.
    X. Wang is a professor of School of Mathematics and Statistics, Hexi University, Zhangye, 734000, P. R. of China. Email:xuezhongwang77@126.com.

